



APPENDIX SHOWING CHANGES IN THE CLAIMS
FOR S.N. 09/753,367

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(Amended) A system for controlling the speed of an AC electric motor connected to a cyclical load, the system comprising:

a signal conversion circuit to convert an AC electric signal to a DC electric signal;

a signal measurement circuit [to derive from] sampling the DC electrical signal and deriving a DC electric characteristic signal corresponding to a motor attribute in response thereto;

a control circuit having a DC current signal stored thereon, the control circuit deriving a reference signal in response to a set point parameter and comparing [responsive to] the DC electric characteristic signal and the DC current signal with the reference signal [and a set point parameter] to generate control signals in response thereto; and

a signal inversion circuit to generate drive signals in accordance with the control signals that modify the speed of the AC electric motor in response to indicated changes in the motor attribute to correspond to the set point parameter.

2. (Amended) The system of claim 1 in which the signal measurement circuit [senses] samples the DC electric signal at a selected sampling frequency to derive the DC electric characteristic signal.

7. (Amended) The system of claim 1 wherein the set point parameter is [in which the control circuit is provided] a torque set point [as a set point parameter and derives] and wherein the reference signal is a torque reference signal such that the torque reference signal is used to [derive] generate the control signals being representative of a determined adjustment to a dimension of the drive signals generated by the signal inversion circuit to selectively drive the motor.

Cancel claim 8.

11. (Amended) The system of claim [8] 26 in which the dimension of the drive signal is frequency.

12. (Amended) The system of claim [8] 26 in which the dimension of the drive signals is voltage.

13. (Amended) The system of claims [7 and 8] 26 in which the set point parameter is determined by evaluation of the motor driving the cyclic load in an unregulated mode.

14. (Amended) A method for controlling speed of a variable drive system driven AC electric motor connected to a cyclic load, the method comprising the stems of:
converting an AC electric signal to a DC electric signal
deriving a set of DC electric characteristic signals from the DC electric signal;
generating first and second sets of control signals in response to the set of DC electrical characteristic signals and a set point parameter; and
a predetermined DC current signal;
inverting the DC electric signal in response to the first and second sets of control signals to generate a set of drive signals to modify the speed of the AC electric motor in response to indicated changes in the motor attribute to correspond to the set point parameter.

18. (Amended) The method of claim [17] 27 in which the step of generating first and second sets of control signals further comprises the step of:
comparing the DC current signal with the first reference signal and the stored DC current signal magnitude and comparing the desired parameter signal with the second reference signal for modifying the speed of the AC electric motor.

Cancel claims 22 and 23.

Add new claims 26-29 as follows:

26. A system for controlling the speed of an AC electric motor connected to a cyclical load, the system comprising:

- a signal conversion circuit to convert an AC electric signal to a DC electric signal;
- a signal measurement circuit to derive from the DC electrical signal, a DC electric characteristic signal corresponding to a motor attribute;

- a control circuit responsive to the DC electric characteristic signal and a target torque range, the control circuit deriving a speed reference signal and using the speed reference signal to derive control signals; and

- a signal inversion circuit to generate drive signals in accordance with the control signals that modify the speed of the AC electric motor in response to indicated changes in the motor attribute to correspond to the set point parameter wherein the control signals are representative of a determined adjustment to a dimension of the drive signals generated by the signal inversion circuit to selectively drive the motor.

27. A method for controlling speed of a variable drive system driven AC electric motor connected to a cyclic load, the method comprising the steps of:

- converting an AC electric signal to a DC electric signal;

- deriving a set of DC electric characteristic signals from the DC electrical signal, wherein the step of deriving the set includes the step of sensing the DC electric signal at a selected sampling frequency having a time period to produce the set of DC electric characteristic signals which includes a DC current signal and a DC voltage signal;

- generating first and second sets of control signals in response to the set of DC electric characteristic signals and a set point parameter; wherein the step of generating the first and second sets includes the steps:

- deriving a first reference signal from the set operational parameters; and
 - storing the DC current signal magnitude and deriving a desired parameter signal from the sensed DC voltage signal and the voltage-frequency profile in each of the time period of the selected sampling frequency; and
 - inverting the DC electrical signal in response to the first and second sets of control signals to generate a set of drive signals to modify the speed of the

AC electric motor in response to indicated changes in the motor attribute to correspond to the set point parameter.

28. A method for controlling speed of a variable drive system driven AC electric motor connected to a cyclic load, the method comprising the steps of:

converting an AC electric signal to a DC electric signal;

deriving a set of DC electric characteristic signals from the DC electric signal;

generating first and second sets of control signals in response to the set of DC electric characteristic signals and a second point parameter, wherein the step of generating first and second sets of control signals includes the step of receiving the set of operational parameters, the voltage-frequency profile, and the set point parameter; and

inverting the DC electric signal in response to the first and second sets of control signals to generate a set of drive signals to modify the speed of the AC electric motor in response to indicated changes in the motor attribute to correspond to the set point parameter.

29. A method of controlling speed of a variable drive system driven AC electric motor connected to a cyclic load, the method comprising the steps of:

converting an AC electric signal to a DC electric signal;

deriving a set of DC electric characteristic signals from the DC electric signal;

generating first and second sets of control signals in response to the set of DC electric characteristic signals and a set point parameter, wherein the step of generating first and second sets of control signals includes the step of pre-loading the set of operation parameters, the voltage-frequency profile, and the set point parameter; and

inverting the DC electric signal in response to the first and second sets of control signals to generate a set of drive signals to modify the speed of the AC electric motor in response to indicated changes in the motor attribute to correspond to the set point parameter.